Modelling primate control of grasping for robotics applications
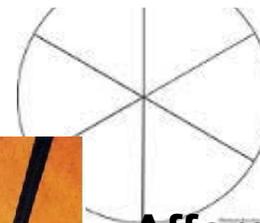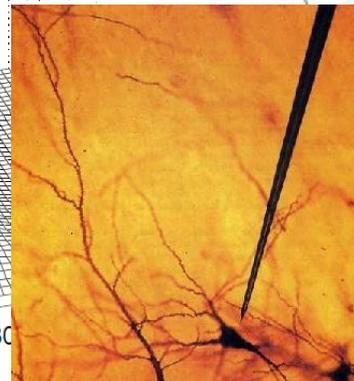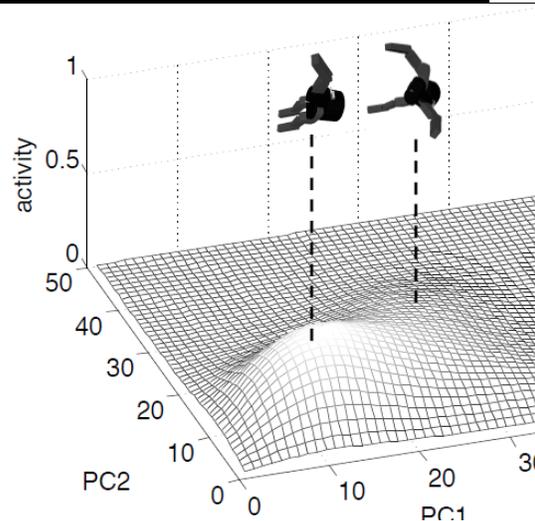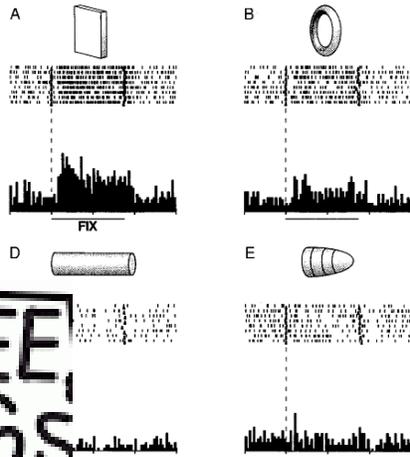Ashley Kleinhans, Serge Thill, Benjamin Rosman, Renaud Detry, Bryan Tripp
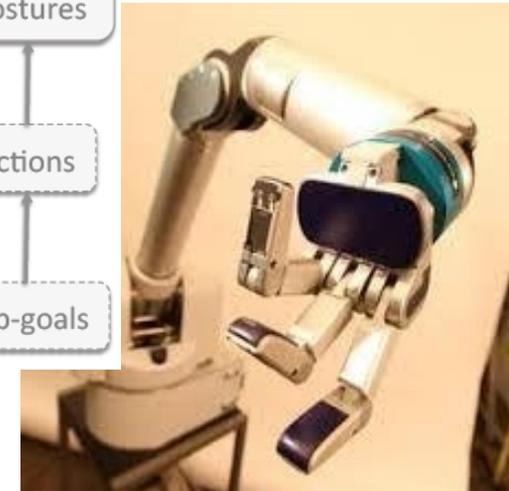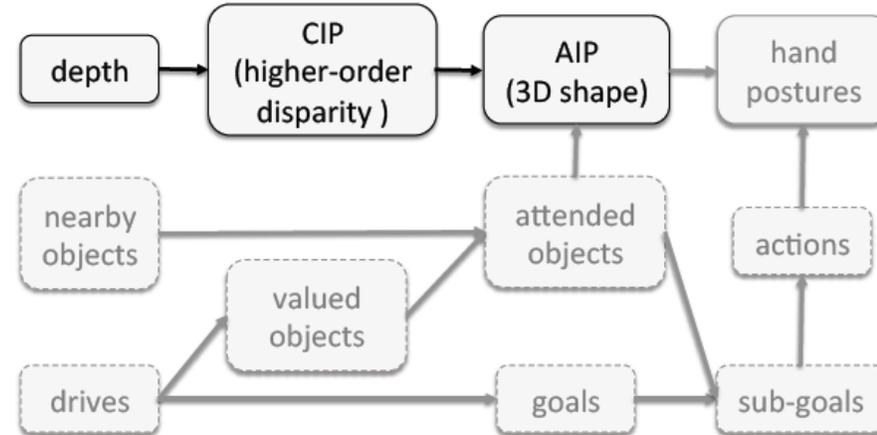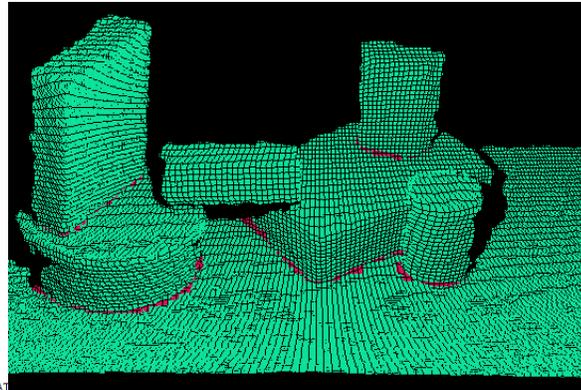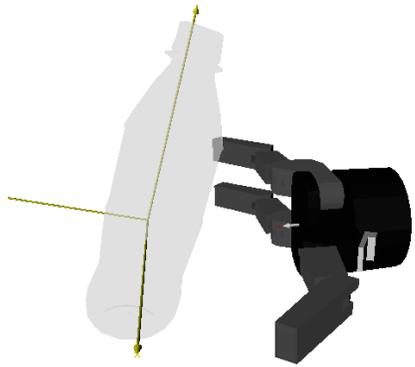
- **Affordances in the brain**

- **3D object modelling in the brain**

- **Neural Engineering Framework**

- **Holographic Reduced Representations**